# SURFACTANT DYNAMICS FROM THE ARNOLD PERSPECTIVE

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New Connections in Math 2021

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# **MOTIVATION AND SETUP**

#### Background

- Basic idea: analyze PDEs through **the calculus of variations**.
- Why?
  - PDEs are hard to solve!
  - Techniques including energy estimates, bootstrapping, functional analysis, etc. are often needed to do anything useful.
  - Alternative characterizations can provide other insights.
- (Arnold '66): critical points of a particular energy are solutions to the Euler equations.

#### Background (cont)

- Next question: can the same be extended to other PDEs?
- Answer: yes!
- In particular, we're interested in those related to **surfactants**.
  - Notable examples: detergents, emulsifiers, and soap bubbles.
  - Relevant to fields like the cosmetic industry, ore extraction and in biology.

Let  $\Omega \subseteq \mathbb{R}^n$  be bounded, connected and open, and set  $\Sigma := \partial \Omega$  to be it's boundary and  $\nu : \Sigma \to \mathbb{R}^n$  to be the associated outward pointing unit normal. We define the function spaces  $\text{Diff}_0(\Omega)$ ,  $\text{FDiff}(\Omega) \subseteq L^2(\Omega; \mathbb{R}^n)$ , to be the sets of volume/orientation preserving diffeomorphisms

$$\mathsf{FDiff}(\Omega) = \{\eta : \Omega \to \mathbb{R}^n \mid \eta \text{ a diffeomorphism}\}.$$
  
 $\mathsf{Diff}_{\mathsf{o}}(\Omega) = \{\eta \in \mathsf{FDiff}(\Omega) \mid \eta(\Omega) = \Omega\}.$ 

# THE SETUP



# **TECHNICAL RESULTS**

KEY TOOLS:

#### **Characterizations of Perturbations**



Orthogonality Conditions.



Tools from differential geometry tell us that

$$T_{\eta} \text{Diff}_{\mathsf{O}}(\Omega) = \{ u \circ \eta \in L^{2}(\Omega; \mathbb{R}^{n}) \mid \text{div } u = \mathsf{O}, u \cdot \nu = \mathsf{O} \}$$
(1)  
$$T_{\eta} \text{FDiff}(\Omega) = \{ u \circ \eta \in L^{2}(\Omega; \mathbb{R}^{n}) \mid \text{div } u = \mathsf{O} \}$$
(2)

which gives us a necessary condition for locally generating a perturbation. Using techniques from ODE, we can also show that this condition is sufficient.

Let X be the space of all flows associated to  $\Omega$  over the time interval [0, 1]; that is,

$$X := \{\eta \in C^1([\mathsf{O},\mathsf{1}];\mathsf{FDiff}(\Omega)) \mid \eta(\mathsf{O}) = \eta_\mathsf{O}, \eta(\mathsf{1}) = \eta_\mathsf{1}\}$$

where  $\eta_0, \eta_1$  are some fixed initial and terminal states of the fluid.

#### Lemma 1

Let  $v_0 : [0, 1] \to \{v \in L^2(\Omega; \mathbb{R}^n) \mid \text{div} (v \circ \eta^{-1}) = 0\}$ ,  $\eta_0, \eta_1 \in \text{FDiff}(\Omega)$  be fixed. Then there exists a perturbation  $\zeta : (-\varepsilon, \varepsilon) \to X$  such that:

$$\zeta(\mathsf{O}) = \eta, \zeta(\mathsf{s}) \in \mathsf{C}^{\infty}, \text{ and } \partial_{\mathsf{s}}\zeta(\mathsf{x},\mathsf{O},\mathsf{t}) := \mathsf{v}(\eta(\mathsf{x},\mathsf{t}),\mathsf{O},\mathsf{t}) = \mathsf{v}_{\mathsf{O}}(\eta(\mathsf{x},\mathsf{t}),\mathsf{t}).$$

# DECOMPOSITIONS OF $L^2$

Now we state the Leray decomposition, which allows us to introduce the pressure term that will appear in our later PDEs.

#### Theorem 1 (Leray Decomposition)

Let  ${\mathcal V}$  be the space of smooth and compactly supported divergence free functions; that is,

$$\mathcal{V} = \{ \varphi \in C^{\infty}_{c}(\Omega; \mathbb{R}^{n}) \mid \operatorname{div} \varphi = \mathbf{0} \}$$
(3)

Let H be the closure of  $\mathcal{V}$  in  $L^2(\Omega; \mathbb{R}^n)$ . Then H and its orthogonal complement in  $L^2(\Omega; \mathbb{R}^n)$  satisfy the following:

$$H = \{ u \in L^2(\Omega; \mathbb{R}^n) \mid \text{div } u = 0, u \cdot \nu = 0 \}$$
(4)

$$H^{\perp} = \{ \nabla p \in L^{2}(\Omega; \mathbb{R}^{n}) \mid p \in H^{1}(\Omega) \}$$
(5)



# PREVIOUS RESULTS: ARNOLD'S SETUP

#### Theorem 2 (Arnold)

If they exist, critical points of the energy functional  $E:X\to \mathbb{R}^+$  defined via

$$E(\eta) = \int_0^1 \int_\Omega \frac{1}{2} |\partial_t \eta|^2 \, dx dt \tag{6}$$

satisfy the incompressible Euler equations with fixed boundary and uniform constant density; that is,

$$\begin{cases} \partial_t u + u \cdot \nabla u + \nabla p = 0 & \text{on } \Omega \\ \mathbf{div} \ u = 0 & \text{on } \Omega \\ u \cdot \nu = 0 & \text{on } \partial \Omega \end{cases}$$
(7)

where  $u(\eta(\mathbf{x}, t), t) = \partial_t \eta(\mathbf{x}, t)$  and p is the pressure.

#### Proof Sketch.

**\blacksquare** For any perturbation  $\zeta$  as before, we know that we must have

 $\partial_{s} E(\zeta) \mid_{s=0} = 0$ 

since  $\zeta(0) = \eta$  is a critical point.

• We calculate to find that  $\partial_t u + u \cdot \nabla u$  must vanish when tested against any smooth, compactly supported, and divergence free function; that is

$$\partial_t u + u \cdot \nabla u \in \mathcal{V}^\perp$$

(Recall:  $\mathcal{V} = \{ \varphi \in C^{\infty}_{c}(\Omega; \mathbb{R}^{n}) \mid \operatorname{div} \varphi = 0 \}$ )

Using the Leray decomposition, we see that this term must be exactly the negative pressure gradient, which leads to the equality

 $\partial_t u + u \cdot \nabla u + \nabla p = 0 \text{ on } \Omega.$ 

We now consider a significant complication of the Arnold functional, where we introduce a globally defined potential term  $\varphi$  (which can represent forces such as gravity or electromagnetism), allow the density  $\rho$  of the fluid to vary over space, add a term  $\sigma$  to compensate for surface tension, and allow the fluid to move freely through space.

#### Theorem 3

Given  $\sigma \in \mathbb{R}^+$ ,  $\overline{\rho} : \Omega \to \mathbb{R}^+$  and  $\varphi \in C^1(\mathbb{R}^n)$ , critical points (if they exist) of the action  $A : X \to \mathbb{R}$  defined via

$$A(\eta) = \int_{0}^{1} \left( \int_{\Omega} \frac{\overline{\rho}}{2} |\partial_{t}\eta|^{2} - \varphi(\eta) \, dx - \int_{\partial\Omega(t)} \sigma dS \right) dt \tag{8}$$

must satisfy the incompressible Euler equations with surface tension; that is,

$$\begin{cases}
\rho(\partial_t u + u \cdot \nabla u) + \nabla p = -\nabla\varphi & \text{on } \Omega(t) \\
\mathbf{div} \ u = 0 & \text{on } \Omega(t) \\
p = -\sigma H & \text{on } \partial \Omega(t)
\end{cases}$$
(9)

where  $\Omega(t) := \eta(\Omega, t)$ , u is the Eulerian velocity defined via  $u(\eta(x, t), t) = \partial_t \eta(x, t)$ ,  $\overline{\rho}$ ,  $\rho$  are Lagrangian and Eulerian densities, and  $H = -\operatorname{div} \nu$  is the mean curvature of  $\partial \Omega(t)$ .

#### **Conservation of Mass**

Note: We require the density  $\rho$  to satisfy the conservation of mass law:

$$rac{d}{dt}\int_{\eta(U,t)}
ho d\mathsf{S}=\mathsf{O}$$

for any  $U \subseteq \Omega$ . Combining this with the transport equation yields

 $\partial_t \rho + \operatorname{div}(\rho u) = 0 \text{ on } \Omega(t).$ 

#### Proof of Theorem (Sketch).

First, we localize: by only considering compactly supported velocity fields, we can isolate the contribution of the terms defined on Ω to deduce the first equation:

$$\rho(\partial_t u + u \cdot \nabla u) + \nabla p = -\nabla \varphi \text{ on } \Omega(t)$$

Considering general velocity fields, combining the Reynolds transport equation and the surface divergence theorem, and doing further computations then yields the other equations. Now we introduce a term to penalize the motion of surfactants that move alongside the boundary. Here the motion of the surfactants is determined by the motion of the flow map.

### **RESULT #2 PENALIZING SURFACTANT BOUNDARY WIGGLING**

#### Theorem 4

Given  $\overline{\rho}:\Omega\to\mathbb{R}^+,\ \xi:\mathbb{R}\to\mathbb{R}^+,\ \overline{\gamma}_{o}:\partial\Omega\to\mathbb{R}^+,\ \varphi\in C^1(\mathbb{R}^n)$ , let  $A:X\to\mathbb{R}$  via

$$A(\eta) = \int_{0}^{1} \left( \int_{\Omega} \frac{\overline{\rho}}{2} |\partial_{t}\eta|^{2} - \varphi(\eta) \, dx + \int_{\partial\Omega} \frac{\overline{\gamma}_{0}}{2} |\partial_{t}\eta|^{2} \, dS - \int_{\partial\Omega(t)} \xi(\gamma) \, dS \right) dt. \tag{10}$$

Then critical points (if they exist) of the action functional A must satisfy

$$\begin{cases} \rho(\partial_{t}u + u \cdot \nabla u) + \nabla p = -\nabla\varphi & \text{on } \Omega(t) \\ \mathbf{div} \ u = \mathbf{0} & \text{on } \Omega(t) \\ \partial_{t}\rho + \mathbf{div}(\rho u) = \mathbf{0} & \text{on } \Omega(t) \\ \gamma(\partial_{t}u + u \cdot \nabla u) - p\nu = \nabla_{\Sigma(t)}\sigma + H\nu\sigma & \text{on } \partial\Omega(t) \\ \partial_{t}\gamma + \nabla\gamma \cdot u + \gamma \mathbf{div}_{\Sigma(t)}u = \mathbf{0} & \text{on } \partial\Omega(t) \end{cases}$$
(11)

where u is the Eulerian velocity,  $\sigma = \xi(\gamma) - \xi'(\gamma)\gamma$  is the surface tension,  $\xi$  is some free energy,  $\overline{\rho}, \rho$  are densities, and p is the pressure.

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- Any questions?

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